

# Lecture Notes

## ECE 381

I. Husain

### TOPIC 1

Single & Three Phase Circuits

**Reference:** Chapter 1: Zia A. Yamayee and Juan L. Bala Jr.  
*Electromechanical Energy Devices and Power Systems*, John Wiley & Sons, Inc., 1994.

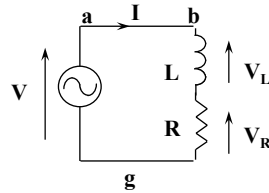
## Single-phase Circuits

# Single Phase Circuit

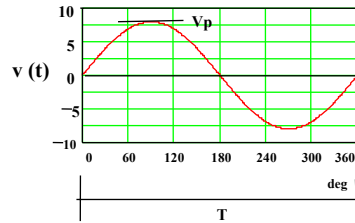
## Review

- **Single phase circuit components:**

- Voltage or current sources
- Impedances (resistance, inductance, and capacitance)
- The components are connected in series or in parallel.



- The figure shows a simple circuit where a voltage source (generator) supplies a load (resistance and inductance in series).



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# Single Phase Circuit

## Review

- The voltage source produces a sinusoidal voltage wave

$$v(t) = \sqrt{2} V_{\text{rms}} \sin(\omega t)$$

where:  $V_{\text{rms}}$  is the rms value of the voltage (volts)

$\omega$  is the angular frequency of the sinusoidal function (rad/sec)

$$\omega = 2\pi f = \frac{2\pi}{T} \text{ rad/sec} \quad f = \frac{1}{T} \text{ Hz}$$

$f$  is the frequency (60 Hz in USA, 50 Hz in Europe).

$T$  is the time period (seconds).

- The peak value (max value) of the voltage is  $V_p = \sqrt{2} V_{\text{rms}}$

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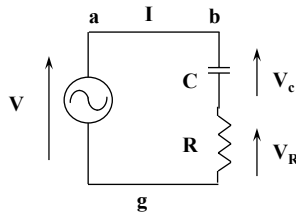
# Single Phase Circuit

## Review

The rms value is calculated by

$$V_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^T v(t)^2 dt}$$

- The voltage direction is indicated by an arrow from g to a. This means during the positive half cycle the potential of point a is larger than g.



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# Single Phase Circuit

## Review

- The current is also sinusoidal

$$i(t) = \sqrt{2} I_{\text{rms}} \sin(\omega t - \phi)$$

where:  $I_{\text{rms}}$  is the rms value of the current.

$\phi$  is the phase-shift between current and voltage.

The rms current is calculated by the Ohm's Law:

$$I_{\text{rms}} = \frac{V_{\text{rms}}}{Z}$$

where:  $Z$  is the impedance.

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# Single Phase Circuit

## Review

- The impedances (in Ohms) are :
  - a) Resistance (R)
  - b) Inductive reactance

$$X_L = \omega L$$

- c) Capacitive reactance

$$X_C = \frac{1}{\omega C}$$

# Single Phase Circuit

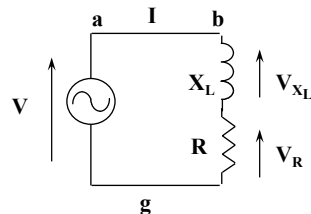
## Review

- The impedance of a resistance and a reactance connected in series is :
- Impedance calculation

$$Z = \sqrt{R^2 + X^2}$$

- The phase angle is :

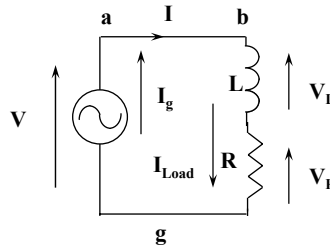
$$\phi = a \tan \frac{X}{R}$$



# Single Phase Circuit

## Review

- The generator current flows from **g** to **a** in the positive half cycle.
- **The load current and voltages are in opposite direction**
- **The generator current and voltage are in the same direction.**
- The load current in the positive half cycle flows from **b** to **g**.



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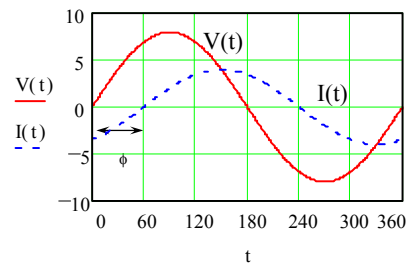
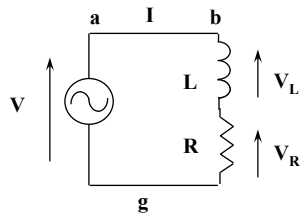
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# Single Phase Circuit

## Review

- **Inductive circuit**
  - The  $\phi$  phase-shift between the current and voltage is negative.
  - The current is lagging with respect to the voltage.



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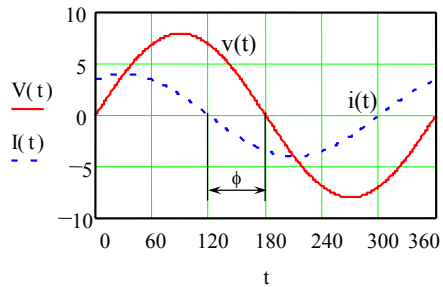
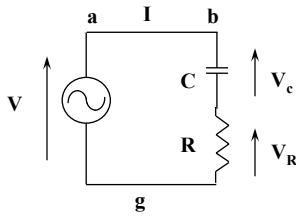
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# Single Phase Circuit

## Review

- **Capacitive circuit**

- The  $\phi$  phase shift between the current and voltage is positive.
- The current is leading with respect to the voltage.



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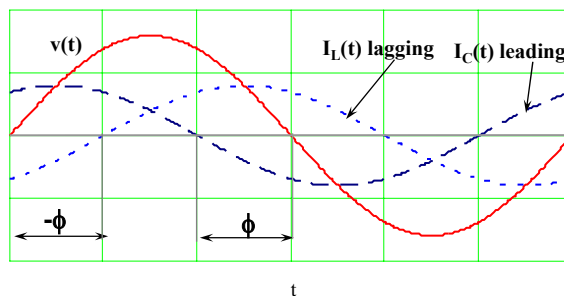
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# Single Phase Circuit

## Review

- **Illustration of capacitive (leading) and inductive (lagging) current.**



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# Single Phase Circuit

## Review

### Complex Notation

- Engineering calculations need the amplitude (rms value) and phase angle of voltage and current.
- The time function is used for transient analysis.
- The amplitude and phase angle can be calculated using complex notation.
- The voltage, current, and impedance are expressed by complex phasors.

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# Single Phase Circuit

## Review

### Complex Notation

**Impedance phasor:** (resistance, capacitor, and inductance connected in series)

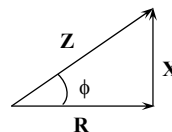
**Rectangular form:**

$$\mathbf{Z} = R + j\omega L + \left(\frac{1}{j\omega C}\right) = R + j(X_L - X_C) = R + jX_T$$

**Exponential form:**  $\mathbf{Z} = |Z|e^{j\phi}$

**where:**

$$\mathbf{Z} = \sqrt{R^2 + X^2} \quad \phi = \tan^{-1}\left(\frac{X}{R}\right)$$



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# Single Phase Circuit

## Review

### Complex Notation

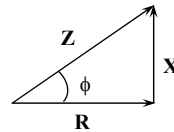
**Impedance phasor:** (resistance, capacitor, and inductance connected in series)

**Polar form:**

$$\mathbf{Z} = |\mathbf{Z}| \angle \phi = |\mathbf{Z}| [\cos(\phi) + j \sin(\phi)]$$

$$\mathbf{Z} = \sqrt{R^2 + X^2} \quad \phi = \tan^{-1} \left( \frac{X}{R} \right)$$

$$R = \mathbf{Z} \cos(\phi) \quad X = \mathbf{Z} \sin(\phi)$$



# Single Phase Circuit

## Review

### Complex Notation

- Voltage phasor:

$$\mathbf{V} = |\mathbf{V}| e^{j\delta} \quad \text{or}$$

$$\mathbf{V} = |\mathbf{V}| \angle \delta = |\mathbf{V}| \cos \delta + j |\mathbf{V}| \sin \delta$$

where :  $V$  is the rms value, and  $\delta$  is the phase angle

Note: The supply voltage phase angle is often selected as the reference with  $\delta=0$



# Single Phase Circuit

Review often

## Complex Notation

- Current phasor

$$\mathbf{I} = \frac{\mathbf{V}}{\mathbf{Z}} = \frac{|V| e^{j\delta}}{|Z| e^{j\phi}} = \frac{|V|}{|Z|} e^{j(\delta-\phi)} = \frac{|V|}{|Z|} [\cos(\delta-\phi) + j \sin(\delta-\phi)]$$

# Single Phase Circuit

Review

**Kirchhoff 's laws:**

## **•Voltages:**

- **The sum of the voltages around any loop is zero.**

## **• Other formulation is:**

- **The sum of generator voltages is equal to the sum of load voltages.**

## **•Currents:**

- **The sum of the currents entering any node point is zero**

# Single Phase Circuit

## Review

### **Kirchhoff's laws:**

#### Example.

- If a generator supplies a resistance, an inductance, and a capacitance connected in series we have:

$$V_g = V_R + V_{X_L} + V_{X_C} = I R + I j \omega L_{\text{ind}} + I \frac{1}{j \omega C}$$

- If a generator supplies a resistance, an inductance, and a capacitance connected in parallel we have:

$$I_g = I_R + I_{X_L} + I_{X_C} = \frac{V}{R} + \frac{V}{j \omega L} + \frac{V}{\frac{1}{j \omega C}}$$

# Single Phase Circuit

## Review

### **Power calculation.**

**Instantaneous power is the product of the instantaneous voltage and current.**

$$p(t) = v(t)i(t) = \sqrt{2} V \sin(\omega t) \sqrt{2} I \sin(\omega t - \phi)$$

**Where:**

$$v(t) = \sqrt{2} V \sin(\omega t) \quad i(t) = \sqrt{2} I \sin(\omega t - \phi)$$

# Single Phase Circuit

## Review

### Power calculation. Instantaneous Power

Using the  $\sin(\alpha+\beta)$  relation we have :

$$p(t) = VI \cos(\phi) [2 \sin^2(\omega t)] - VI \sin(\phi) [2 \sin(\omega t) \cos(\omega t)]$$

Using the  $\sin^2(\alpha)$  and  $\sin(2\alpha)$  relations the expression for power is:

$$p(t) = VI \cos(\phi) [1 - \cos(2\omega t)] - VI \sin(\phi) [\sin(2\omega t)]$$

← (1) →      ← (2) →

# Single Phase Circuit

## Review

The power equation is re-arranged as:

$$p(t) = P [1 - \cos(2\omega t)] - Q [\sin(2\omega t)]$$

← (1) →      ← (2) →

Where:

- $P = VI \cos(\phi)$  is the real power or average power (in watts)
- $Q = VI \sin(\phi)$  is the reactive power (in VAR)

# Single Phase Circuit

## Review

- **Part 1 Real Power**  $P = VI \cos(\phi)$

The average value of  $p(t)$  is the real power. This is the power transferred from the generator to the load.

- **Part (2) is the reactive power.**  $Q = VI \sin(\phi)$

The reactive power average value is zero because it oscillates:

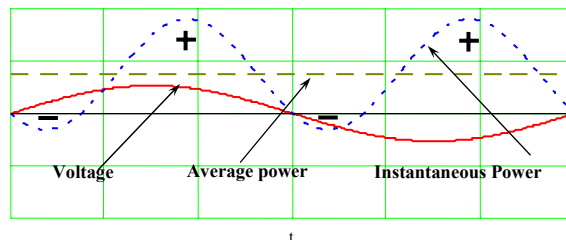
- a) In the positive half cycle the reactive power flows from the generator to the load.
- b) In the negative half cycle the reactive power flows from the load to the generator.

# Single Phase Circuit

## Review

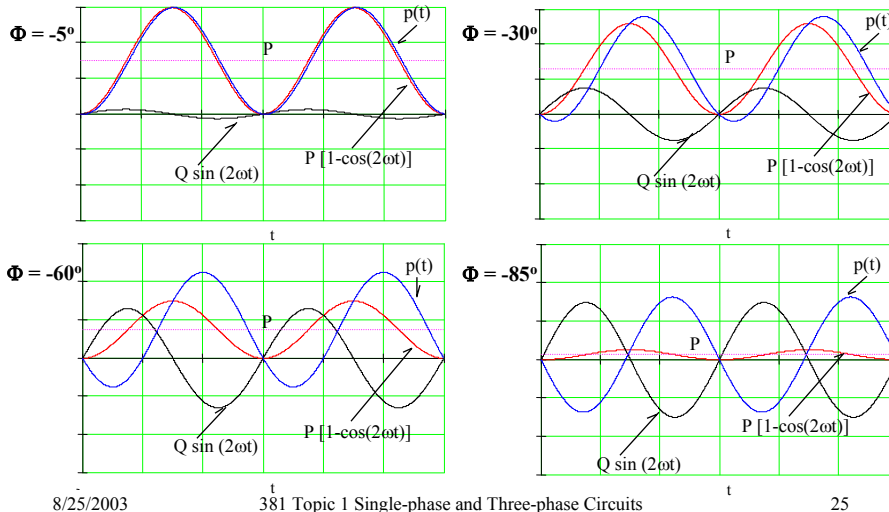
### Instantaneous Power Time Function

- Oscillates with double frequency
- Curve shifted, positive area is larger than the negative one.
- The average transmitted power is :  $P = \frac{1}{T} \int_0^T p(t) dt$



# Single Phase Circuit

Reactive and real power waveforms for different phase angle values.



# Single Phase Circuit

Review

## Complex Power

- The complex notation can be used for power calculation.
- The complex power is defined as : **Voltage times the conjugate of the current.**

$$S = V \bar{I} = V I e^{\pm j\phi} = V I [\cos(\phi) \pm j \sin(\phi)] = P \pm jQ$$

- The power factor magnitude is defined as: **the ratio of the real power and the absolute value of the apparent power.** The power factor may be lagging or leading.

$$\text{pf} = \cos(\phi) = \frac{P}{|S|} = \cos(\arg(S))$$

# Three-phase Circuits

# Three-phase Circuits

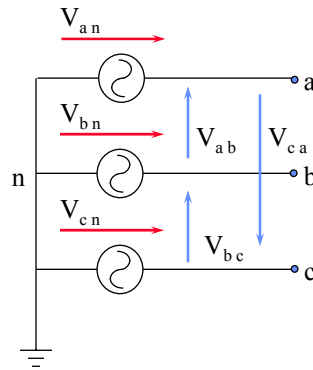
## Wye-Connected System

- The neutral point is grounded
- The three-phase voltages have equal magnitude.
- The phase-shift between the voltages is 120 degrees.

$$\mathbf{V}_{an} = |V| \angle 0^\circ = V$$

$$\mathbf{V}_{bn} = |V| \angle -120^\circ = |V| e^{-j120 \text{ deg}}$$

$$\mathbf{V}_{cn} = |V| \angle -240^\circ = |V| e^{-j240 \text{ deg}}$$



# Three-phase Circuits

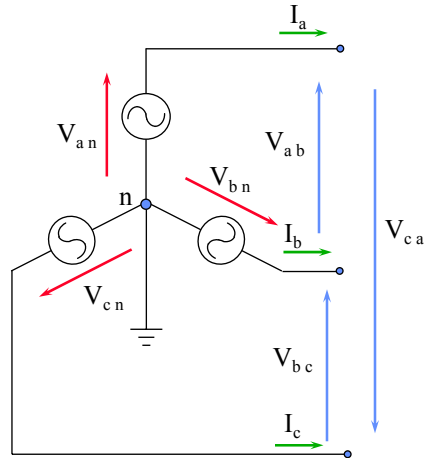
## Wye-Connected System

- Line-to-line voltages are the difference of the phase voltages

$$V_{ab} = V_{an} - V_{bn} = \sqrt{3} V e^{j30 \text{ deg}}$$

$$V_{bc} = V_{bn} - V_{cn} = \sqrt{3} V e^{-j90 \text{ deg}}$$

$$V_{ca} = V_{cn} - V_{an} = \sqrt{3} V e^{j150 \text{ deg}}$$



# Three-phase Circuits

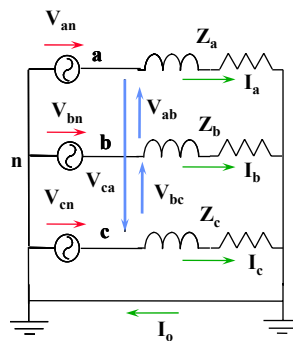
## Wye-Connected Loaded System

- The load is  $Z_a, Z_b, Z_c$
- Each phase voltage drives current through the load.
- The phase current expressions are:

$$I_a = \frac{V_{an}}{Z_a} \quad I_b = \frac{V_{bn}}{Z_b} \quad I_c = \frac{V_{cn}}{Z_c}$$

- The system has ground current defined as:

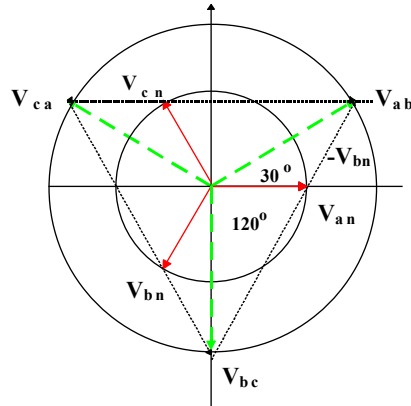
$$I_0 = I_a + I_b + I_c$$



# Three-phase Circuits

## Wye-Connected System

- Phasor diagram is used to visualize the system voltages
- Wye system has two type of voltages: Line-to-neutral, and line-to-line.
- The line-to-neutral voltages are shifted with  $120^\circ$
- The line-to-line voltage leads the line to neutral voltage with  $30^\circ$
- The line-to-line voltage is  $\sqrt{3}$  times the line-to-neutral voltage



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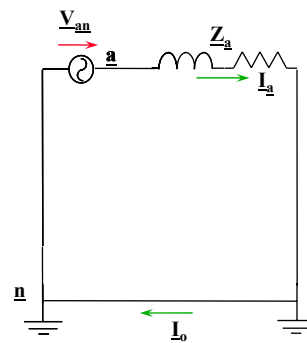
# Three-phase Circuits

## Wye-Connected Loaded System

- If the load is balanced ( $Z_a = Z_b = Z_c$ ) then:

$$I_0 = I_a + I_b + I_c = 0$$

- **This case single phase equivalent circuit can be used (phase a, for instance, only)**
- **Phase b and c are eliminated**



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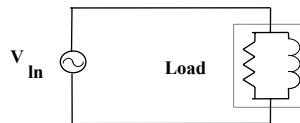
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# Three-phase Circuits

## Wye-Connected System with balanced load

- A single-phase equivalent circuit is used
- Only phase **a** is drawn, because the magnitude of currents and voltages are the same in each phase. Only the phase angles are different ( $-120^\circ$  phase shift)
- The supply voltage is the **line to neutral voltage**.
- The single phase loads are connected to neutral or ground.



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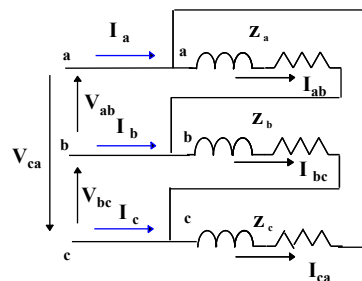
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# Three-phase Circuits

## Balanced Delta-Connected System

- The system has only one voltage : the line-to-line voltage (  $V_{LL}$  )
- The system has two currents :
  - line current
  - phase current
- The phase currents are:

$$I_{ab} = \frac{V_{ab}}{Z_{ab}} \quad I_{bc} = \frac{V_{bc}}{Z_{bc}} \quad I_{ca} = \frac{V_{ca}}{Z_{ca}}$$



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# Three-phase Circuits

## Delta-Connected System

The line currents are:

$$I_a = I_{ab} - I_{ca}$$

$$I_b = I_{bc} - I_{ab}$$

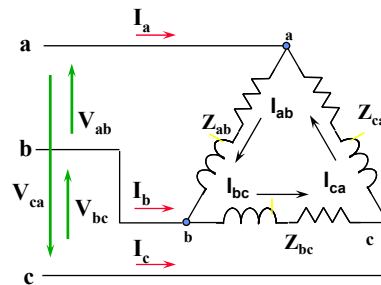
$$I_c = I_{ca} - I_{bc}$$

- In a balanced case the line currents are:

$$I_a = \sqrt{3} I_{ab} e^{-i30\text{deg}}$$

or

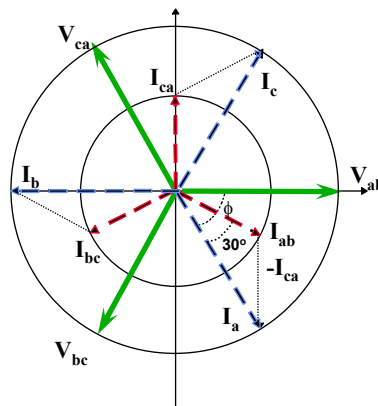
$$I_{\text{line}} = \sqrt{3} I_{\text{phase}} e^{-i30\text{deg}}$$



# Three-phase Circuit

## Delta-Connected System

- The phasor diagram is used to visualize the system currents
- The system has two type of currents: line and phase currents.
- The delta system has only line-to-line voltages, that are shifted by 120°
- The phase currents lead the line currents by 30°
- The line current is  $\sqrt{3}$  times the phase current and shifted by 30 degree.



# Three-phase Circuit

## Power Calculation

- The three phase power is equal the sum of the phase powers

$$P = P_a + P_b + P_c$$

- If the load is balanced:

$$P = 3 P_{\text{phase}} = 3 V_{\text{phase}} I_{\text{phase}} \cos(\phi)$$

- Wye system:  $V_{\text{phase}} = V_{\text{LN}}$   $I_{\text{phase}} = I_L$   $V_{\text{LL}} = \sqrt{3} V_{\text{LN}}$

$$P = 3 V_{\text{phase}} I_{\text{phase}} \cos(\phi) = \sqrt{3} V_{\text{LL}} I_L \cos(\phi)$$

- Delta system:  $I_{\text{Line}} = \sqrt{3} I_{\text{phase}}$   $V_{\text{LL}} = V_{\text{phase}}$

$$P = 3 V_{\text{phase}} I_{\text{phase}} \cos(\phi) = \sqrt{3} V_{\text{LL}} I_L \cos(\phi)$$

# Three-phase Circuit

- **Circuit conversions**

- A delta circuit can be converted to an equivalent wye circuit. The equation for phase a is:

$$Z_a = \frac{Z_{ab} Z_{ca}}{Z_{ab} + Z_{bc} + Z_{ca}}$$

- Conversion equation for a balanced system is:

$$Z_a = \frac{Z_{ab}}{3}$$

# Three-phase Circuit

## Power measurement

- In a four-wire system (3 phases and a neutral) the real power is measured using three single-phase watt-meters.
- In a three-wire system (three phases without neutral) the power is measured using only two single-phase watt-meters.
  - The watt-meters are supplied by the line current and the line-to-line voltage.

- The total power is the algebraic sum of the two watt-meters reading.

